

On sign conditions over real multivariate polynomials

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The Consistency Problem

Polynomial Systems of Equations and Inequalities

Given $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$, decide whether the set

$$\mathcal{P} = \{x \in \mathbb{R}^n \mid f_1(x) = 0, \dots, f_p(x) = 0, f_{p+1}(x) > 0, \dots, f_m(x) > 0\}$$

is empty or not.

If \mathcal{P} is not the empty set, exhibit a point in \mathcal{P} .

A More General Problem

Feasible Sign Conditions

A (closed) sign condition over $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$ is $\sigma \in \{<, =, >\}^m$ (resp. $\sigma \in \{\leq, =, \geq\}^m$).

We say $\sigma = (\sigma_1, \dots, \sigma_m)$ is feasible if the set

$$\mathcal{P}_\sigma = \{x \in \mathbb{R}^n \mid f_1(x)\sigma_1 0, \dots, f_m(x)\sigma_m 0\}$$

is not empty. We call this set the realization of σ .

Two questions. Given $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$:

- Determine all feasible (closed) sign conditions over f_1, \dots, f_m .
- Exhibit a point in \mathcal{P}_σ for each feasible sign condition σ .

- **Quantifier elimination.**

Tarski (1951), Collins (1975), Grigoriev-Vorobjov (1988, 1992), Heintz-Roy-Solernó (1990), Renegar (1992), Canny (1993), Basu-Pollack-Roy (1996).

- **Polynomial equation systems.**

- Bank-Giusti-Heintz-Mbakop (1997, 2001).
- Safey El Din-Schost (2003), Bank-Giusti-Heintz-Pardo (2005).

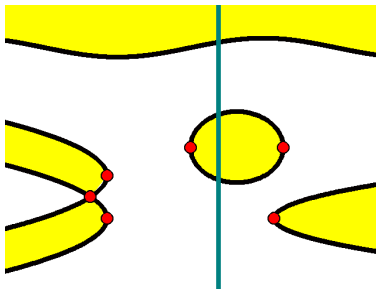
- **Feasible sign conditions over a single polynomial.**

Safey El Din (2007).

Our Approach

Computing points in semialgebraic sets

Search for a point in the **closure** of each connected component of the set.

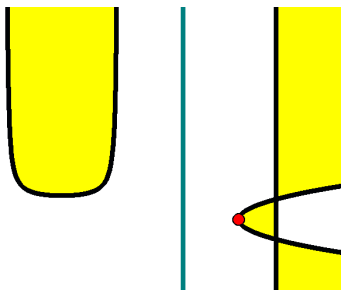


Sketch of the Algorithm

- ▶ Find points where the maximum or minimum of the projection over x_1 is attained.
- ▶ Intersect with $x_1 = c$ and proceed in the same way, recursively, with x_2, \dots, x_n .

A Technical Problem

Asymptotic Situations



The following conditions could be met by a connected component C :

- ▶ there are no extremal points for x_1 over C and,
- ▶ $\{x_1 = c\} \cap C = \emptyset$.

Also, there might be infinitely many extremal points over C .

How to avoid these situations: consider a **generic linear form** instead of x_1 .

Avoiding Asymptotic Situations

Generic linear change of variables

For a nonempty set $C \subset \mathbb{R}^n$ and a linear $\pi : \mathbb{R}^n \rightarrow \mathbb{R}$, let:

- $Z_i(C) = \overline{C} \cap \pi^{-1}(\inf \pi(C))$ if $\pi(C)$ is bounded from below, and $Z_i(C) = \emptyset$ otherwise.
- $Z_s(C) = \overline{C} \cap \pi^{-1}(\sup \pi(C))$ if $\pi(C)$ is bounded from above, and $Z_s(C) = \emptyset$ otherwise.
- $Z(C) = Z_i(C) \cup Z_s(C)$.

Proposition. Let $D \subset \mathbb{R}^n$ be a semialgebraic set. After a **generic linear change of variables**, for $p \in \mathbb{R}^n$, C a connected component of $D \cap \{x_1 = p_1, \dots, x_{k-1} = p_{k-1}\}$, and $\pi(x_1, \dots, x_n) = x_k$:

- $Z(C)$ is a **finite** set (possibly empty).
- If $\pi(C)$ is bounded from below (resp. from above), $Z_i(C) \neq \emptyset$ (resp. $Z_s(C) \neq \emptyset$).

A Finite Set of Sample Points

Let $D \subset \mathbb{R}^n$ be a semialgebraic set. After a generic linear change of variables:

Proposition. Let $p \in \mathbb{R}^n$ and, for $1 \leq k \leq n$, let $\mathcal{C}(k, p)$ be the set of connected components of $D \cap \{x_1 = p_1, \dots, x_{k-1} = p_{k-1}\}$.

Then

$$\{p\} \cup \left(\bigcup_{k=1}^n \bigcup_{C \in \mathcal{C}(k, p)} Z^{(k)}(C) \right)$$

is a finite set intersecting the closure of each connected component of D .

- Our problem amounts to the computation of **extremal points of the projection on the first coordinate**.

Maxima and Minima Subject to Equality Constraints

Given $f_1, \dots, f_s \in \mathbb{R}[x_1, \dots, x_n]$, the **IFT** implies that the maxima and minima of x_1 over $\mathcal{V} = \{f_1(x) = 0, \dots, f_s(x) = 0\}$ occur at points $z \in \mathcal{V}$ for which there exists $\mu \in \mathbb{R}^s \setminus \{0\}$ such that:

$$\sum_{j=1}^s \mu_j \underbrace{\left(\frac{\partial f_j}{\partial x_2}(z), \dots, \frac{\partial f_j}{\partial x_n}(z) \right)}_{\nabla f_j(z)} = (0, \dots, 0) \in \mathbb{R}^{n-1}.$$

Extremal Points for Sign Conditions

Inequality constraints

Generalization. Let $f_1, \dots, f_m \in \mathbb{R}[x_1, \dots, x_m]$.

For $\sigma \in \{\leq, <, =, >, \geq\}^m$, if C is a connected component of

$$\mathcal{P}_\sigma = \{x \in \mathbb{R}^n \mid f_1(x)\sigma_1 0, \dots, f_m(x)\sigma_m 0\},$$

then

$$Z(C) \subset \bigcup_{\{i \mid \sigma_i \text{ is } =\} \subset S \subset \{1, \dots, m\}} \Pi(W_S)$$

- $W_S = \{(x, \mu) \in \mathbb{C}^n \times \mathbb{P}^{s-1} \mid \left\{ \begin{array}{l} f_{i_1}(x) = 0, \dots, f_{i_s}(x) = 0, \\ \sum_{j=1}^s \mu_j \nabla f_{i_j}(x) = 0 \end{array} \right\} \}$
if $S = \{i_1, \dots, i_s\}$.
- $\Pi : \mathbb{C}^n \times \mathbb{P}^{s-1} \rightarrow \mathbb{C}^n$ is the projection onto the first factor.

- **Aim.** Find points in the closure of each connected component of \mathcal{P}_σ for every sign condition σ over f_1, \dots, f_m .
- **Strategy.** Compute points in the sets $\Pi(W_S)$, by (partially) solving the polynomial systems defining them.
- **Difficulty.** Even though the sets $Z(C)$ are finite, the sets $\Pi(W_S)$ might be infinite sets.

We are able to overcome this difficulty in several different situations.

I - Polynomials Satisfying Regularity Assumptions

Assumption

For every $x \in \mathbb{C}^n$ such that $f_{i_1}(x) = 0, \dots, f_{i_s}(x) = 0$, the set $\{\nabla f_{i_1}(x), \dots, \nabla f_{i_s}(x)\}$ is linearly independent.

Under this assumption, for $S \subset \{1, \dots, m\}$:

- $\mathcal{V}_S = \{x \in \mathbb{C}^n \mid f_j(x) = 0 \forall j \in S\} = \emptyset$ if $\#S > n$.
- After a generic linear change of variables,

$$W_S = \{(x, \mu) \in \mathbb{C}^n \times \mathbb{P}^{s-1} \mid \left\{ \begin{array}{l} f_{i_1}(x) = 0, \dots, f_{i_s}(x) = 0, \\ \sum_{j=1}^s \mu_j \nabla f_{i_j}(x) = 0 \end{array} \right. \}$$

is a finite set if $\#S \leq n$.

Theoretical Basis of the Algorithm

The recursion

If $p = (p_1, \dots, p_n) \in \mathbb{R}^n$ is generic, for every $1 \leq k \leq n$, the previous [assumption also holds](#) for

$$f^{(k)} := \{f_j(p_1, \dots, p_{k-1}, x_k, \dots, x_n), 1 \leq j \leq m\}$$

Then,

$$\mathcal{M} = \bigcup_{k=1}^n \bigcup_{\substack{S \subset \{1, \dots, m\} \\ 1 \leq \#S \leq n-k+1}} \Pi(W_S^{(k)})$$

is a finite set intersecting the closure of each connected component of every \mathcal{P}_σ , where $W_S^{(k)} \subset \mathbb{C}^{n-k} \times \mathbb{P}^{\#S-1}$ is defined from $f^{(k)}$.

Basic Step of the Algorithm

The computation of \mathcal{M} amounts to solving in $\mathbb{C}^n \times \mathbb{P}^{s-1}$
0-dimensional polynomial equation systems of the type:

$$\begin{aligned} f_1(x) = 0, \dots, f_s(x) = 0 \\ \sum_{j=1}^s \mu_j \frac{\partial f_j}{\partial x_2}(x) = 0, \dots, \sum_{j=1}^s \mu_j \frac{\partial f_j}{\partial x_n}(x) = 0 \end{aligned}$$

These systems have the following **structure**:

- s equations involving only the variables x with $\deg_x \leq d$,
- $n - 1$ equations with $\deg_x \leq d - 1$, homogeneous and linear in the variables μ ,

which we exploit to solve them within good complexity bounds.

Deformation Techniques

For the computation of isolated roots of a polynomial system

Given $F = [f_1(x), \dots, f_s(x), f_{s+1}(x, \mu), \dots, f_r(x, \mu)]:$

- Choose an initial system

$$G = [g_1(x), \dots, g_s(x), g_{s+1}(x, \mu), \dots, g_r(x, \mu)]$$

with the **same structure** and maximum number of known or “easy to compute” solutions.

- Consider the homotopy $H(t) = tF + (1 - t)G$ so that $H(0) = G$ and $H(1) = F$.
- Compute a description of the **solutions to $H = 0$** over $\overline{\mathbb{Q}(t)}$ from the solutions to $G = 0$, by **Newton-Hensel** lifting.
- Substitute $t = 1$ in order to obtain the isolated roots of $F = 0$.

Main Complexity Result

Theorem A (J.-Perrucci-Sabia)

Under the previous regularity assumption on the input polynomials $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$, there is a probabilistic algorithm which computes a finite set of points \mathcal{M} such that $\mathcal{M} \cap \overline{C} \neq \emptyset$ for every connected component C of \mathcal{P}_σ for every feasible $\sigma \in \{<, =, >\}^m$.

The algorithm performs $O\left(\sum_{s=1}^{\min\{m,n\}} \binom{m}{s} \left(\binom{n-1}{s-1} d^n\right)^2 (L+d)\right)$ arithmetic operations in \mathbb{Q} (up to logarithmic factors), where

- $d = \max\{\deg(f_i)\}$ and
- L is the input size.

Parametric Representation of Finite Sets

A set $\mathcal{M} = \{\xi_1, \dots, \xi_D\} \subset \mathbb{C}^n$, where $\xi_j = (\xi_{j1}, \dots, \xi_{jn})$, definable by polynomial equations over \mathbb{Q} can be characterized by:

- $\ell = \ell_1 x_1 + \dots + \ell_n x_n \in \mathbb{Q}[x]$ a **separating** linear form for \mathcal{M} ,
i.e. $\ell(\xi_i) \neq \ell(\xi_j)$ for $i \neq j$,
- $m_\ell = \prod_{1 \leq j \leq D} (U - \ell(\xi_j)) \in \mathbb{Q}[U]$,
- $v_1, \dots, v_n \in \mathbb{Q}[U]$ with $\deg(v_i) < D$ and $v_i(\ell(\xi_j)) = \xi_{ji} \forall j$.

These data provide the following parametric description of the set:

$$\mathcal{M} = \{(v_1(u), \dots, v_n(u)) \mid u \in \mathbb{C}, m_\ell(u) = 0\}.$$

which we call a **geometric solution** of \mathcal{M} .

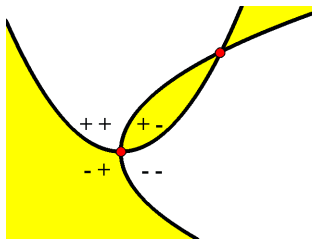
Example. $\mathcal{M} = \{(-1, 3), (1, 3), (2, 0)\}$

- $l = x_1$ is a separating linear form,
- $m_l = (U + 1)(U - 1)(U - 2) = U^3 - 2U^2 - U + 2$,
- $v_1 = U$,
 $v_2 \in \mathbb{Q}[U]$ such that:
 $v_2(-1) = 3, v_2(1) = 3, v_2(2) = 0$, and $\deg v_2 < 3$
 $\Rightarrow v_2 = -U^2 + 4$,

$$\mathcal{M} = \{(u, -u^2 + 4) \mid u^3 - 2u^2 - u + 2 = 0\}$$

Feasible Sign Conditions

From the finite set \mathcal{M} the algorithm computes, we can list all the feasible sign conditions over f_1, \dots, f_m :



- ▶ Determine the signs of f_1, \dots, f_m at each point in \mathcal{M} (Canny, 1993).
- ▶ If $f_j(\xi) = 0$ for $\xi \in \mathcal{M}$, in a neighborhood of ξ , f_j takes both positive and negative values.

Proposition

If \mathcal{L} is the set of the sign conditions of f_1, \dots, f_m at the points in \mathcal{M} , all **feasible sign conditions** over f_1, \dots, f_m are $\bigcup_{\sigma \in \mathcal{L}} L_\sigma$, where $L_\sigma = \{\sigma' \in \{<, =, >\}^m \mid \sigma'_i = \sigma_i \text{ if } \sigma_i \text{ is } < \text{ or } >\}$.

II - Bivariate polynomials

Let $f_1, \dots, f_m \in \mathbb{R}[x_1, x_2]$. Even if they do not satisfy the regularity assumption and the considered sets of critical points are not finite, due to

- a better understanding of the sets $Z(C)$ for the connected components C of \mathcal{P}_σ , and
- polynomial equations defining the auxiliary varieties \mathcal{W}_S ,

proceeding as in the previous case, we can locate a finite subset \mathcal{M} of critical points such that $\mathcal{M} \cap \overline{C} \neq \emptyset$ for each connected component of \mathcal{P}_σ for all feasible σ .

If C is a connected component of \mathcal{P}_σ for $\sigma \in \{<, =, >\}^m$, and $\xi \in Z(C)$, one of the following conditions holds:

- 1 $\exists f_{i_0} / q_1(\xi) = q_2(\xi) = 0$ for non-associate irred. factors q_1 and q_2 of f_{i_0} or $q(\xi) = \frac{\partial q}{\partial x_2}(\xi) = 0$ for an irred. factor q of f_{i_0} .
 $\Rightarrow \xi \in \pi_x(\mathcal{W}_{\{i_0\}} \cap \{t = 0\})$, $\mathcal{W}_{\{i_0\}}$ = union of irred. comp. of $\{(1-t)f_{i_0} + tg_1 = 0, (1-t)\frac{\partial f_{i_0}}{\partial x_2} + tg_2 = 0\}$ not in $\{t = 0\}$
- 2 $\exists f_{i_1}, f_{i_2} / q_1(z) = q_2(z) = 0$ for a single irred. factor q_1 of f_{i_1} and a single irred. factor q_2 of f_{i_2} , q_1 and q_2 non-associate.
 $\Rightarrow \xi \in \pi_x(\mathcal{W}_{\{i_1, i_2\}} \cap \{t = 0\})$, $\mathcal{W}_{\{i_1, i_2\}}$ = union of irred. comp. of $\{(1-t)f_{i_1} + tg_1 = 0, (1-t)f_{i_2} + tg_2 = 0\}$ not in $\{t = 0\}$.

$$\mathcal{M} = \bigcup_{S \subset \{1, \dots, m\}, 1 \leq \#S \leq 2} \pi_x(\mathcal{W}_S \cap \{t = 0\})$$

III - An Arbitrary Polynomial

Given $f \in \mathbb{R}[x_1, \dots, x_n]$, after a generic linear change of variables, the finitely many extremal points of x_1 over the connected components of $\{f < 0\}$, $\{f = 0\}$ and $\{f > 0\}$ lie in

$$W = \left\{ f(x) = 0, \frac{\partial f}{\partial x_2}(x) = 0, \dots, \frac{\partial f}{\partial x_n}(x) = 0 \right\}$$

However, W may be an infinite set.

Example. If $f = (x_1 - x_3^2)^3 - x_2^2 \in \mathbb{R}[x_1, x_2, x_3]$, then:

- $\frac{\partial f}{\partial x_2} = -2x_2$ and $\frac{\partial f}{\partial x_3} = -6x_3(x_1 - x_3^2)^2$,
- $W = \{x_2 = 0, x_1 - x_3^2 = 0\}$.

Deformation for Computing Extremal Points

Given $f \in \mathbb{Q}[x_1, \dots, x_n]$, consider the Tchebychev polynomial \mathcal{T}_d of degree $d = 2\lceil \deg f/2 \rceil$ and define $h = (1 - t)f + tg$, where $g = n + 1 + \sum_{k=1}^n \mathcal{T}_d(x_k)$ (positive over \mathbb{R}^n).

- $W(g) = \{x \in \mathbb{C}^n \mid g(x) = \frac{\partial g}{\partial x_1}(x) = \dots = \frac{\partial g}{\partial x_n}(x) = 0\}$ is a finite set, and the same holds for $W(h \mid_{\{t=t_0\}})$ for all but a finite number of t_0 .

Proposition. If \mathcal{W} is the union of the irreducible components of $\{(t, x) \mid h(t, x) = \frac{\partial h}{\partial x_1}(t, x) = \dots = \frac{\partial h}{\partial x_n}(t, x) = 0\}$ not contained in $t = c$, for every connected component C of $\{f = 0\}$, $\{f < 0\}$ or $\{f > 0\}$, we have $Z(C) \subset \pi_x(\mathcal{W} \cap \{t = 0\})$.

Idea. If $\xi \in Z(C)$, for t_0 sufficiently small, there are points in $W(h(t_0, x)) = \pi_x(\mathcal{W} \cap \{t = t_0\})$ arbitrarily close to ξ .

Theorem B (J.-Perrucci-Sabia)

There is a probabilistic algorithm that, given an arbitrary polynomial $f \in \mathbb{Q}[x_1, \dots, x_n]$, computes a finite set \mathcal{M} such that $\mathcal{M} \cap \bar{C} \neq \emptyset$ for every connected component C of $\{f > 0\}$, $\{f = 0\}$ or $\{f < 0\}$.

The algorithm performs $O(d^{2n}L)$ arithmetic operations in \mathbb{Q} (up to logarithmic factors), where $d := 2^{\lceil \frac{\deg f}{2} \rceil}$ and L is the size of the encoding of f .

IV - Families of Arbitrary Polynomials

Sets defined by equalities

Let $\mathcal{P} = \{x \in \mathbb{R}^n \mid f_1(x) = 0, \dots, f_m(x) = 0\}$ be defined by arbitrary polynomials $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$.

- For $i = 1, \dots, m$, define g_i^+ and g_i^- in $\mathbb{Q}[x_1, \dots, x_n]$, such that $\forall x \in \mathbb{R}^n$, $g_i^+(x) > 0$ and $g_i^-(x) < 0$.

Deformation.

- For $i = 1, \dots, m$, let

$$h_i^+ = (1 - t)f_i + tg_i^+ \quad \text{and} \quad h_i^- = (1 - t)f_i + tg_i^-.$$

- $\mathcal{P}_t = \{x \in \mathbb{R}^n \mid \forall 1 \leq i \leq m, h_i^+(t, x) \geq 0 \text{ and } h_i^-(t, x) \leq 0\}$.

The polynomials h_i^+ and h_i^- are in general position and

$$\mathcal{P} \subset \mathcal{P}_t \quad \forall 0 \leq t \leq 1 \quad \text{and} \quad \mathcal{P}_0 = \mathcal{P}.$$

Extremal Points of Projections

General approach. Find extremal points in a connected component of $\mathcal{P} = \mathcal{P}_0$ as “limits” of points in \mathcal{P}_t for small t .

- If C is a connected component of \mathcal{P} and $\xi \in Z(C)$, $\forall \varepsilon > 0$, if t is sufficiently small, there is a **critical point** of x_1 , $\xi_t \in \mathcal{P}_t$, such that $d(\xi_t, \xi) < \varepsilon$.
- For a generic t_0 ,

$$\xi_{t_0} \in \bigcup_{\substack{S \subset \{1, \dots, m\} \times \{+, -\} \\ 1 \leq \#S \leq n}} \pi_x(\mathcal{W}_S \cap \{t = t_0\}),$$

\mathcal{W}_S is the union of the irreducible components of $\{(t, x, \mu) \mid h_i^\tau(t, x) = 0 \ \forall (i, \tau) \in S, \sum_{(i, \tau) \in S} \mu_i^\tau \bar{\nabla} h_i^\tau(t, x) = 0\}$ not contained in a hyperplane $t = c$.

Proposition. For every connected component C of the set $\mathcal{P} = \{x \in \mathbb{R}^n \mid f_1(x) = 0, \dots, f_m(x) = 0\}$, we have

$$Z(C) \subset \bigcup_{\substack{S \subset \{1, \dots, m\} \times \{+, -\} \\ 1 \leq \#S \leq n}} \pi_x(\mathcal{W}_S \cap \{t = 0\}).$$

This enables us to **compute a finite set of sampling points** of the connected components of \mathcal{P} :

- recursive procedure;
- at each step, solve the polynomial systems defining the corresponding \mathcal{W}_S over $\overline{\mathbb{Q}(t)}$ and set $t = 0$.

Closed Sign Conditions

The previous result extends to sets defined by equalities and non-strict inequalities:

$$\mathcal{P}_\sigma = \{x \in \mathbb{R}^n \mid f_1(x)\sigma_1 0, \dots, f_m(x)\sigma_m 0\}, \text{ with } \sigma \in \{\leq, =, \geq\}^m.$$

Deform \mathcal{P}_σ by means of the sets $\mathcal{P}_{\sigma,t}$ defined by:

- $h_i^+(t, x) \geq 0$ and $h_i^-(t, x) \leq 0$ for all i such that σ_i is an $=$,
- $h_i^+(t, x) \geq 0$ for all i such that σ_i is a \geq ,
- $h_i^-(t, x) \leq 0$ for all i such that σ_i is a \leq .

Theorem C (J.-Perrucci-Sabia)

There is a probabilistic algorithm which, given polynomials $f_1, \dots, f_m \in \mathbb{Q}[x_1, \dots, x_n]$, computes a **finite** set of points \mathcal{M} such that $\mathcal{M} \cap C \neq \emptyset$ for each connected component C of the realization of every feasible sign condition $\sigma \in \{\leq, =, \geq\}^m$.

The algorithm performs $O((L+d)d^{2n}(\sum_{s=1}^{\min\{m,n\}} 2^s \binom{m}{s} \binom{n-1}{s-1}^2))$ arithmetic operations in \mathbb{Q} (up to logarithmic factors), where $d = 2^{\lceil \frac{1}{2} \max\{\deg f_i\} \rceil}$ and L is the input length.

Therefore, we derive a probabilistic algorithm for the computation of all **feasible sign conditions** $\sigma \in \{\leq, =, \geq\}^m$ for **arbitrary** polynomials f_1, \dots, f_m in $\mathbb{Q}[x_1, \dots, x_n]$.